Summary of Part I: back to 1990

Giacalone, Jou and Smolka

- advocated the use of pseudometrics instead of equivalence relations to compare the behaviour of states of systems with approximate quantitative data,
- introduced a pseudometric for deterministic PTSs, and
- proposed nonexpansiveness as a quantitative generalization of congruence.

Vineet Gupta, Thomas A. Henzinger, and Radha Jagadeesan. Robust timed automata.

In O. Maler, editor, *Proceedings of the International Workshop on Hybrid and Real-Time Systems*, volume 1201 of *Lecture Notes in Computer Science*, pages 331–345, Grenoble, March 1997. Springer-Verlag.

Timed systems

Mireille Broucke. Regularity of solutions and homotopic equivalence for hybrid systems.

In *Proceedings of the 37th IEEE Conference on Decision and Control*, volume 4, pages 4283-4288, Tampa, December 1998. IEEE.

Hybrid systems

Josée Desharnais, Vineet Gupta, Radha Jagadeesan, and Prakash Panangaden. Metrics for labeled Markov systems.

In J.C.M. Baeten and S. Mauw, editors, *Proceedings of 10th International Conference on Concurrency Theory*, volume 1664 of *Lecture Notes in Computer Science*, pages 258-273, Eindhoven, August 1999. Springer-Verlag.

Probabilistic systems

Probabilistic transition system used by GJS

Definition

A probabilistic transition system (PTS) is a tuple $\langle S, \mathcal{A}, T \rangle$ consisting of

- a set S of states,
- ullet a set ${\cal A}$ of actions, and
- ullet a function T:S imes A imes S o [0,1] such that for all $s\in S$,

$$\sum_{\textit{a} \in \mathcal{A} \land \textit{s}' \in \textit{S}} \textit{T(s,a,s')} \in \{0,1\}.$$

This is a generative model.

Probabilistic transition system used by DGJP

Definition

A probabilistic transition system (PTS) is a tuple $\langle S, A, (T_a)_{a \in A} \rangle$ consisting of

- a set S of states,
- ullet a set ${\cal A}$ of actions, and
- for each $a \in \mathcal{A}$, a function $T_a : S \times S \rightarrow [0,1]$ such that for all $s \in S$,

$$\sum_{s'\in S} T_a(s,s') \in \{0,1\}.$$

This is a reactive model.

Probabilistic transition system

The generative model and the reactive model coincide in case there is one (= no) action.

Definition

A probabilistic transition system (PTS) is a tuple $\langle S,T \rangle$ consisting of

- a set S of states,
- ullet a function T:S imes S o [0,1] such that for all $s\in S$,

$$\sum_{s'\in S} T(s,s') \in \{0,1\}.$$

Logical characterization of probabilistic bisimilarity

Prakash already presented

Definition

The logic $\mathcal L$ is defined by

$$\varphi ::= \top \mid \varphi \wedge \varphi \mid \Diamond_{q} \varphi$$

where $q \in [0,1] \cap \mathbb{Q}$.

and

Theorem

 $s_1 \sim s_2$ iff s_1 and s_2 satisfy the same formulae.

Logical characterization of probabilistic bisimilarity

The interpretation of formulae can be formalized as

Definition

The function $[\![\cdot]\!]:\mathcal{L}\to\mathcal{S}\to\mathbb{B}$ is defined by

The theorem on the previous slide can be reformulated as

Theorem

$$s_1 \sim s_2 \text{ iff } \forall \varphi \in \mathcal{L} : \llbracket \varphi \rrbracket(s_1) = \llbracket \varphi \rrbracket(s_2).$$

From equivalence relation to 1-bounded pseudometric

We restrict our attention to

Definition

A pseudometric $d_S: S \times S \to \mathbb{R}$ is 1-bounded if for all $s_1, s_2 \in S$,

$$d_{S}(s_1,s_2)\leq 1.$$

When generalizing from equivalence relations to 1-bounded pseudometrics, we go from $\mathbb B$ to [0,1]. Hence,

Theorem

$$s_1 \sim s_2 \text{ iff } \forall \varphi \in \mathcal{L} : \llbracket \varphi \rrbracket(s_1) = \llbracket \varphi \rrbracket(s_2).$$

suggests

Definition

$$d_{S}(s_{1}, s_{2}) = \sup_{\varphi \in \mathcal{L}} \llbracket \varphi \rrbracket(s_{1}) - \llbracket \varphi \rrbracket(s_{2}).$$



Definition

The logic \mathcal{L} is defined by

$$\varphi ::= \top \mid \varphi \wedge \varphi \mid \Diamond \varphi \mid \varphi \ominus \mathbf{q} \mid \neg \varphi$$

where $q \in [0,1] \cap \mathbb{Q}$.

Definition

The function $[\![\cdot]\!]:\mathcal{L}\to\mathcal{S}\to[0,1]$ is defined by

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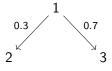
where $q \in [0,1] \cap \mathbb{Q}$.

Definition

The function $[\![\cdot]\!]:\mathcal{L}\to\mathcal{S}\to[0,1]$ is defined by

$$egin{array}{lll} \llbracket au
rbracket (s) &=& 1 \ \llbracket arphi_1 \wedge arphi_2
rbracket (s) &=& \llbracket arphi_1
rbracket (s) \min \llbracket arphi_2
rbracket (s) \ \llbracket arphi arphi
rbracket (s) &=& \ \llbracket arphi arphi
rbracket (s) &=& \ \llbracket arphi arphi
rbracket (s) &=& \ \lVert arph$$

 $\llbracket \varphi
rbracket (s) \in [0,1]$: "the probability that arphi holds in s"



$$\llbracket \lozenge \varphi \rrbracket (1) = 0.3 \times \llbracket \varphi \rrbracket (2) + 0.7 \times \llbracket \varphi \rrbracket (3)$$

Definition

The logic \mathcal{L} is defined by

$$\varphi ::= \top \mid \varphi \land \varphi \mid \Diamond \varphi \mid \varphi \ominus \mathbf{q} \mid \neg \varphi$$

where $q \in [0,1] \cap \mathbb{Q}$.

Definition

The function $\llbracket \cdot
rbracketa : \mathcal{L} o S o [0,1]$ is defined by

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Definition

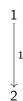
The function $[\![\cdot]\!]:\mathcal{L}\to\mathcal{S}\to[0,1]$ is defined by





$$d_{S}(1,2) = [\![\lozenge \top]\!](1) - [\![\lozenge \top]\!](2)$$

= $1 \times [\![\top]\!](2) - 0$
= 1.





Which formula distinguishes 1 and 2 the most?

$$d_{S}(2,1) = [\neg \lozenge \top](2) - [\neg \lozenge \top](1)$$

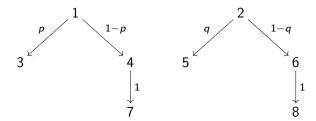
$$= (1 - [\lozenge \top](2)) - (1 - [\lozenge \top](1))$$

$$= [\lozenge \top](1) - [\lozenge \top](2)$$

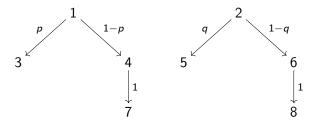
$$= 1.$$

The formula $\neg \lozenge \top$ is abbreviated to $\sqrt{.}$





Assume that $p \ge q$. Which formula distinguishes 1 and 2 the most?



Assume that $p \ge q$. Which formula distinguishes 1 and 2 the most?

$$d_{S}(1,2) = [\![\lozenge\sqrt{]\!]}(1) - [\![\lozenge\sqrt{]\!]}(2)$$

$$= (p \times [\![\sqrt{]\!]}(3) + (1-p) \times [\![\sqrt{]\!]}(4))$$

$$-(q \times [\![\sqrt{]\!]}(5) + (1-q) \times [\![\sqrt{]\!]}(6))$$

$$= (p \times 1 + (1-p) \times 0) - (q \times 1 + (1-q) \times 0)$$

$$= p - q.$$



$$\begin{array}{ccc}
1 & 0.5 & 2 & 1.0 \\
0.5 & & & & \\
3 & & & & & \\
\end{array}$$

$$\begin{array}{ccc}
1 & 0.5 & 2 & 1.0 \\
0.5 & & & & \\
3 & & & & & \\
\end{array}$$

$$\begin{split} & [\![\diamondsuit(\sqrt{\vee} \diamondsuit \sqrt{\vee})]\!] (1) - [\![\diamondsuit(\sqrt{\vee} \diamondsuit \sqrt{\vee})]\!] (2) \\ & = \quad (0.5 \times [\![\sqrt{\vee} \diamondsuit \sqrt{\vee}] (1) + 0.5 \times [\![\sqrt{\vee} \diamondsuit \sqrt{\vee}] (3)) - 1 \times [\![\sqrt{\vee} \diamondsuit \sqrt{\vee}] (2)) \\ & = \quad (0.5 \times ([\![\sqrt{\vee}] (1) \max [\![\diamondsuit \sqrt{\vee}] (1)) + 0.5 \times ([\![\sqrt{\vee}] (3) \max [\![\diamondsuit \sqrt{\vee}] (3)))) \\ & \quad - 1 \times ([\![\sqrt{\vee}] (2) \max [\![\diamondsuit \sqrt{\vee}] (2))) \\ & = \quad (0.5 \times (0 \max 0.5) + 0.5 \times (1 \max 0)) - 1 \times (0 \max 0) \\ & = \quad 0.75. \end{split}$$

$$\begin{array}{ccc}
1 & 0.5 & 2 & 1.0 \\
0.5 & & & & \\
3 & & & & &
\end{array}$$

Definition

For $n \in \mathbb{N}$, the formula φ_n is defined by

$$\varphi_n = \left\{ \begin{array}{l} \lozenge \sqrt{\qquad} & \text{if } n = 0 \\ \lozenge (\sqrt{\vee} \varphi_{n-1}) & \text{otherwise.} \end{array} \right.$$

Proposition

For all $n \in \mathbb{N}$, $[\![\varphi_n]\!](1) = 1 - 2^{-(n+1)}$ and $[\![\varphi_n]\!](2) = 0$.

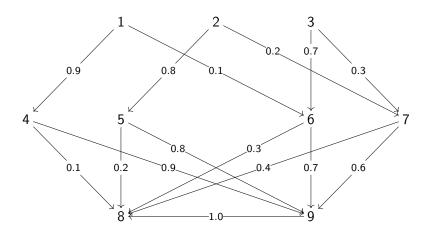
$$\begin{array}{ccc}
1 & 0.5 & 2 & 1.0 \\
0.5 & & & & \\
3 & & & & & \\
\end{array}$$

$$d_{S}(1,2) = \sup_{n \in \mathbb{N}} [\varphi_{n}](1) - [\varphi_{n}](2)$$

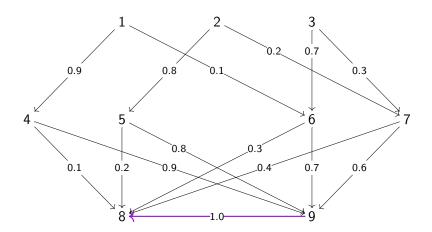
$$= \sup_{n \in \mathbb{N}} (1 - 2^{-(n+1)}) - 0$$

$$= 1.$$

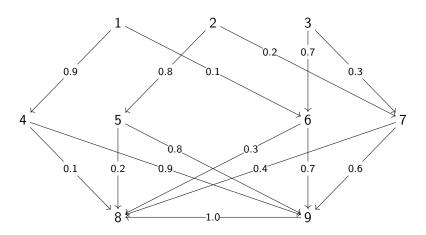
$$\llbracket \neg \sqrt{\rrbracket}(8) = 0$$
 and $\llbracket \neg \sqrt{\rrbracket}(9) = 1$



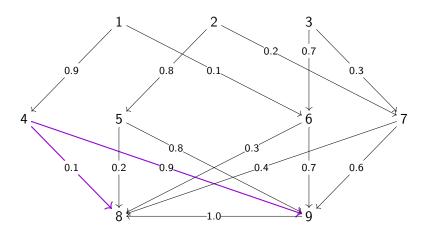
$$\llbracket \neg \sqrt{\rrbracket}(8) = 0 \text{ and } \llbracket \neg \sqrt{\rrbracket}(9) = 1$$



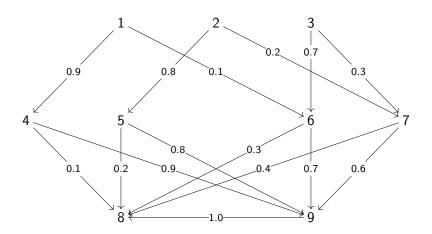
$$[\![\lozenge\neg\sqrt]\!](4)=0.9,\ [\![\lozenge\neg\sqrt]\!](5)=0.8,\ [\![\lozenge\neg\sqrt]\!](6)=0.7$$
 and $[\![\lozenge\neg\sqrt]\!](7)=0.6$



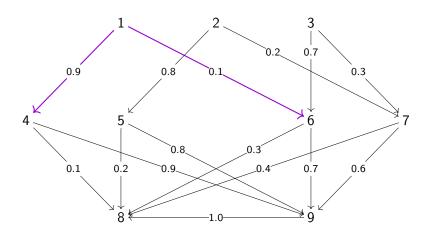
$$[\![\lozenge\neg\sqrt]\!](4)=0.9,\ [\![\lozenge\neg\sqrt]\!](5)=0.8,\ [\![\lozenge\neg\sqrt]\!](6)=0.7$$
 and $[\![\lozenge\neg\sqrt]\!](7)=0.6$



$$[\![\lozenge\lozenge\lnot\lnot\sqrt]\!](1)=0.88,\ [\![\lozenge\lozenge\lnot\lnot\sqrt]\!](2)=0.76\ \text{and}\ [\![\lozenge\lozenge\lnot\lnot\sqrt]\!](3)=0.67$$



$$[\![\lozenge\lozenge\lnot\lnot\sqrt]\!](1)=0.88,\ [\![\lozenge\lozenge\lnot\lnot\sqrt]\!](2)=0.76\ \text{and}\ [\![\lozenge\lozenge\lnot\sqrt]\!](3)=0.67$$



According to the definition of GJS

$$d_S(1,2) \leq 0.1$$

 $d_S(2,3) \leq 0.1$
 $d_S(1,3) \geq 0.25$

According to the definition of DGJP

$$d_S(1,2) = 0.12$$

 $d_S(2,3) = 0.09$
 $d_S(1,3) = 0.21$

Some properties of d_S

DGJP proved

Proposition

 d_S is a pseudometric.

and

Theorem

$$s_1 \sim s_2 \text{ iff } d_S(s_1, s_2) = 0.$$

and also

Proposition

 \oplus and \parallel are nonexpansive.

Markov process

Definition

A *Markov process* is a tuple $\langle S, \Sigma, \tau \rangle$ consisting of

- a set *S* of states,
- a σ -algebra Σ on S, and
- a function $\tau: \mathcal{S} \times \Sigma \rightarrow [0,1]$ such that
 - for all $s \in S$, $\tau(s, \cdot)$ is a measure and
 - for all $A \in \Sigma$, $\tau(\cdot, A)$ is a measurable function.

$$\llbracket \lozenge arphi
rbracket (s) = \int_{\mathcal{S}} \llbracket arphi
rbracket d au(s).$$

Overview of Part II: the rest of the nineties

Desharnais, Gupta, Jagadeesan and Panangaden generalized the behavioural pseudometric of Giacalone, Jou and Smolka to

- all PTSs and
- labelled Markov processes.

Are there other ways to define behavioural pseudometrics?